

Extending affine subspaces in higher dimensions

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- 2 The size of collections of k -planes
- 3 Proof strategies

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- Usually, by size we mean measure or some notion of dimension (e.g. Hausdorff, box counting, packing, Assouad...).
- More precisely, what can we say about sets that we know have a certain geometric property, or that are obtained by some natural geometric operation on a set with known size?

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Fractal dimension

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In general, $\dim_H(E) \leq \dim_P(E)$

Definition

The effective Hausdorff dimension of a point $x \in \mathbb{R}^n$ relative to an oracle $A \subseteq \mathbb{N}$ is given by

$$\dim^A(x) = \liminf_{r \rightarrow \infty} \frac{K_r^A(x)}{r}$$

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Definition

The effective packing dimension of a point $x \in \mathbb{R}^n$ relative to an oracle $A \subseteq \mathbb{N}$ is given by

$$\text{Dim}^A(x) = \limsup_{r \rightarrow \infty} \frac{K_r^A(x)}{r}$$

The point-to-set principle

Effective dimension is directly related to classical dimension through the following “point-to-set” principle(s):

Theorem (J. Lutz and N. Lutz, 2015)

For all $E \subset \mathbb{R}^n$,

$$\dim_H(E) = \min_{A \subseteq \mathbb{N}} \sup_{x \in E} \dim^A(x)$$

and

$$\dim_P(E) = \min_{A \subseteq \mathbb{N}} \sup_{x \in E} \text{Dim}^A(x)$$

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k -planes and the Grassmanian

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- The Grassmanian is a subset of the larger “affine” Grassmanian—the set of *all* k -planes. We denote the affine Grassmanian by $\mathcal{A}(n, k)$.
- We say that the “direction” of $I \in \mathcal{A}(n, k)$ is the unique element of $\mathcal{G}(n, k)$ that is a translation of I .
- There are a number of equivalent metrics we can define on the affine Grassmanian, meaning we can talk about the Hausdorff and packing dimension of subsets of $\mathcal{A}(n, k)$.

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Let $k \geq 2$. If $E \subseteq \mathbb{R}^n$ contains a k -plane in every direction, then E has positive Lebesgue measure.

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The Furstenberg set problem

Let $E \subseteq \mathbb{R}^2$ be such that there is a Hausdorff dimension t set of lines, each intersecting E in a set of Hausdorff dimension s . Then

$$\dim_H(E) \geq \min\left\{s + t, s + 1, \frac{3s + t}{2}\right\}$$

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More precisely, given any $E \subseteq \mathbb{R}^n$, let $\mathcal{I}_k(E) \subseteq \mathcal{A}(n, k)$ index the k -planes intersecting E in a set of Hausdorff dimension k . Define

$$\mathcal{P}_k(E) = E \cup \bigcup_{I \in \mathcal{I}_k(E)} I$$

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Conjecture

Let $E \subseteq \mathbb{R}^n$. For all $1 \leq k \leq n-1$,

$$\dim_H(E) = \dim_H(\mathcal{P}_k(E)) \quad \text{and} \quad \dim_P(E) = \dim_P(\mathcal{P}_k(E))$$

Results for lines

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In higher dimensions:

- (Bushling and F., 2024): Extending a collection of line segments to full lines does not increase the packing dimension to more than $2 \dim_P(E) - 1$

In general, we have the following bound for the extension of k -planes:

Theorem (F., 2025)

Let $E \subseteq \mathbb{R}^n$ be a union of open subsets of k -planes. Then, if F_k is the set formed by extending each of these subsets,

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New results

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Moreover, we have an improved result for hyperplanes:

Theorem (F., 2025)

Let $E \subseteq \mathbb{R}^n$. Then

$$\dim_P(\mathcal{P}_{n-1}(E)) = \dim_P(E)$$

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Effectivization of k -plane extension

- Using the point-to-set principle

$$\dim_P(E) = \min_{A \subseteq \mathbb{N}} \sup_{x \in E} \text{Dim}^A(x) = \min_{A \subseteq \mathbb{N}} \sup_{I \in \mathcal{I}} \sup_{x \in E \cap I} \text{Dim}^A(x)$$

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- So it suffices to show that for every $A \subseteq \mathbb{N}$, $I \in \mathcal{A}(n, k)$, and S an open subset of I ,

$$\sup_{x \in I} \text{Dim}^A(x) \leq 2 \sup_{x \in S} \text{Dim}^A(x) - k$$

Choosing points

- Using the properties of the limit superior this follows if for every $x \in I$, there exist $y, z \in S$ such that,

$$K_r^A(x) \leq K_r^A(y) + K_r^A(z) - kr$$

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- Choose y so that it's first k coordinates are random relative to x and A ; call this vector \hat{y} . We may also assume the line containing x and y intersects S in a set of positive measure.
- Hence, we may choose z on this line such that one of its first k coordinates is random relative to x, y , and A ; call this coordinate \hat{z} .

Completing the proof

Main idea: There exists some $t \in \mathbb{R}$ such that $x = y + t(z - y)$. Hence a precision r estimate of y, z , and t is enough to compute a (nearly) precision r estimate of x and other *unrelated* information.

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On one hand,

$$\begin{aligned} K_r^A(x, \hat{y}, \hat{z}) &\leq K_r^A(y, z, t) \\ &\leq K_r^A(y) + K_r^A(z) + K_r^A(t) \\ &\leq K_r^A(y) + K_r^A(z) + r \end{aligned}$$

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On the other,

$$\begin{aligned} K_r^A(x, \hat{y}, \hat{z}) &= K_r^A(x) + K_r^A(\hat{y}, \hat{z}) \\ &= K_r^A(x) + K_r^A(\hat{y}) + K_r^A(\hat{z}) \\ &= K_r^A(x) + kr + r \end{aligned}$$

Sketch of the proof for hyperplanes I

Geometric lemma

Let $n \geq 2$ and a hyperplane $(a, b) = (a_1, \dots, a_{n-1}, b)$ be given and assume $(u, v) = (u_1, \dots, u_{n-1}, v)$ is a hyperplane such that $a_1 x_1 + \dots + a_{n-1} x_{n-1} + b = u_1 x_1 + \dots + u_{n-1} x_{n-1} + v$. Let $t \leq r$ be the largest precision up to which (a, b) and (u, v) agree. Then for every oracle A ,

$$K_r^A(u, v) \geq K_t^A(a, b) + K_{r-t, r}^A(x_1, \dots, x_{n-1} | a, b) - (n-2)(r-t) - O(\log r)$$

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Idea: Two intersecting hyperplanes determine an $(n-2)$ -plane (with a possible loss of precision). $(n-2)(r-t)$ bits of extra information determine any specific point in this $(n-2)$ -plane.

Sketch of the proof for hyperplanes II

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- We choose an oracle D at the given precision carefully so that the first requirement holds *and* we do not sacrifice any more complexity than necessary.

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- Applying the geometric lemma to a nearly random x_1, \dots, x_n (which we have the freedom to pick) gives the second condition.

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- Applying the geometric lemma to a nearly random x_1, \dots, x_n (which we have the freedom to pick) gives the second condition.
- A short argument shows that the resulting lower bound on the complexity of the point nearly matches a natural upper bound at every precision, completing the proof.

Thank you!